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# EXISTENCE AND STABILITY FOR A LAMÉ SYSTEM WITH TIME DELAY AND INFINITE MEMORY 

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#### Abstract

We pursue the investigation started in a recent paper [10] and later [2] concerning the wave equations with elasticity operator. We prove the existence of solutions for Lamé system in three-dimension bounded domain with time delay term by using semi-group theory. We also study the exponential stability of solutions by means of an appropriate Lyapunov functional.


## 1. Introduction and related results

Let us define the elasticity operator $\Delta_{e}$, which is the $3 \times 3$ matrix-valued differential operator by

$$
\Delta_{e} u=\mu \Delta u+(\lambda+\mu) \nabla(\operatorname{div} \mathrm{u}), \quad u=\left(u_{1}, u_{2}, u_{3}\right)^{T}
$$

where $\mu, \lambda$ are the Lamé constants which satisfy

$$
\begin{array}{r}
\mu>0 \\
\lambda+\mu \geq 0 . \tag{1.1}
\end{array}
$$

It is well known that for the case $\lambda+\mu=0, \Delta_{e}=\mu \Delta$ gives the Laplacian operator.

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In this paper, we consider the following Lamé system with time delay term and infinite memory:

$$
\begin{equation*}
u^{\prime \prime}(x, t)-\Delta_{e} u(x, t)+\int_{0}^{+\infty} h(s) \Delta u(x, t-s) d s+k u^{\prime}(x, t-\tau)=0 \quad \text { in } \Omega \times \mathbb{R}^{+} \tag{1.2}
\end{equation*}
$$

Eq. (1.2) supplemented with initial and boundary conditions

$$
\begin{cases}u(x,-t)=u_{0}(x, t), & \text { in } \Omega,  \tag{1.3}\\ u^{\prime}(x, 0)=u_{1}(x), & \text { in } \Omega, \\ u^{\prime}(x, t-\tau)=f_{0}(x, t-\tau), & \text { in } \Omega \times(0, \tau), \\ u=0, & \text { on } \partial \Omega \times \mathbb{R}^{+}\end{cases}
$$

Here $\Omega$ is a bounded domain in $\mathcal{R}^{3}$ with smooth boundary $\partial \Omega$ and $\left(u_{0}, u_{1}, f_{0}\right)$ are given initial data. Let

$$
h(s)=\left(\begin{array}{ccc}
h_{1}(s) & 0 & 0  \tag{1.4}\\
0 & h_{2}(s) & 0 \\
0 & 0 & h_{3}(s)
\end{array}\right)
$$

where $h_{i}: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$are given functions which represent the dissipative terms.
The qualitative studies of viscoelastic wave equations/systems have been many studied by many mathematicians and many results have been obtained in the last few years (see [1], [2], [3], 4], [5], 7], 9], [12]).
Without delay, a single viscoelastic wave equation was cosidered by [11] in the following Cauchy problem:

$$
\left\{\begin{array}{lll}
u^{\prime \prime}-\Delta_{x} u+\int_{0}^{t} g(t-s) \Delta u(s, x) d s=0 & \text { in } & \mathbb{R}^{n} \times \mathbb{R}^{+},  \tag{1.5}\\
u(x, 0)=u_{0}(x) \quad u^{\prime}(x, 0)=u_{1}(x) & \text { on } & \mathbb{R}^{n} .
\end{array}\right.
$$

For a not necessarily decreasing relaxation function, the authors obtained a polynomial decay rate of solutions for compactly supported initial data. In [7], the authors studied the following equation :

$$
\begin{equation*}
u^{\prime \prime}-\Delta u+\int_{0}^{t} h(t-s) \Delta u(s, x) d s+b(x) u^{\prime}+|u|^{p-1} u=0, \quad \Omega \times \mathbb{R}^{+} \tag{1.6}
\end{equation*}
$$

Here $b: \Omega \longrightarrow \mathbb{R}^{+}$is a function, which may vanish on a part of the bounded domain $\Omega$. By assuming $b(x) \geq b_{0}$ on $w \subset \Omega$ and for two positive constants $\zeta_{1}$ and $\zeta_{2}$ such that

$$
\begin{equation*}
-\zeta_{1} h(t) \leq h^{\prime}(t) \leq-\zeta_{2} h(t) \tag{1.7}
\end{equation*}
$$

under some geometry restrictions on $w$, the authors obtained an exponential decay result. In [5],the author established and extend the result in [6], under weaker conditions on both $a$ and $g$, to a system where a source term is competing with the damping term. In order to compensate the lack of Poincare's inequality in $\mathbb{R}^{n}$ and for a wider class of relaxation functions, Zennir in [15] used weighted spaces to establish a very general decay rate of solutions for viscoelastic wave equations of Kirchhoff-type in

$$
\begin{equation*}
\rho(x)\left(\left|u^{\prime}\right|^{q-2} u^{\prime}\right)^{\prime}-M\left(\left\|\nabla_{x} u\right\|_{2}^{2}\right) \Delta_{x} u+\int_{0}^{t} h(t-s) \Delta_{x} u(s) d s=0, x \in \mathbb{R}^{n}, t>0 \tag{1.8}
\end{equation*}
$$

where $q, n \geq 2$ and $M$ is a positive $C^{1}$ function satisfying for $s \geq 0, m_{0}>0, m_{1} \geq 0, \gamma \geq 1$, $M(s)=m_{0}+m_{1} s^{\gamma}$ and the function $g: \mathbb{R}^{+} \longrightarrow \mathbb{R}^{+}$is of class $C^{1}$ is assumed to satisfy

$$
\begin{equation*}
m_{0}-\bar{g}=l>0, \quad g(0)=g_{0}>0 \tag{1.9}
\end{equation*}
$$

where $\bar{g}=\int_{0}^{\infty} g(t) d t$. In addition, there exists a positive function $H \in C^{1}\left(\mathbb{R}^{+}\right)$such that

$$
\begin{equation*}
g^{\prime}(t)+H(g(t)) \leq 0, t \geq 0, \quad H(0)=0 \tag{1.10}
\end{equation*}
$$

and $H$ is linear or strictly increasing and strictly convex $C^{2}$ function on $(0, r], 1>r$.
Bchatnia and Daoulatli [1] considered the case of the Lamé system in a three-dimensional bounded domain with local nonlinear damping and external force, and obtained several boundedness and stability estimates depending on the growth of the damping and the external forces. The control region considered in [1] satisfies the famous geometric optical condition (GOC).
In Section 2, one of the main goal is to prove the global existence and uniqueness of solutions of (1.2)-(1.3). Section 3 is devoted to state and prove the main results of this work, that is, the stability of the system $(1.2)-(\sqrt{1.3})$.

## 2. Well-Posedness and uniqueness of solution

To prove the well-posedness and uniqueness of solutions of (1.2)-(1.3) using semi-group theory, we first consider the following hypothesis:

A1: The functions $h_{i}$ is integrable on $\mathbb{R}^{+}$and is such that

$$
\begin{equation*}
\mu-\int_{0}^{+\infty} h_{i}(s) d s>0 \text { and } \infty>\alpha_{i}=\int_{0}^{+\infty} h_{i}(s) d s>0 \quad i=1,2,3 . \tag{2.11}
\end{equation*}
$$

A2: The function $h$ is of class $C^{1}\left(\mathbb{R}^{+}\right)$and satisfies

$$
\begin{equation*}
h_{i}^{\prime}(s) \leq \gamma_{i} h(s) \quad \forall s \in \mathbb{R}^{+} \quad i=1,2,3 \tag{2.12}
\end{equation*}
$$

for a positive constants $\gamma_{i}$.
Following a methods developed in [8], [13], we consider two new auxiliary variables $\eta$ and $z$, such that

$$
\begin{cases}\eta(t, s)=u(t)-u(t-s) & \forall t, s \in \mathbb{R}^{+}  \tag{2.13}\\ \eta_{0}(s)=\eta(0, s)=u(0)-u_{0}(s) & \forall s \in \mathbb{R}^{+} \\ z(t, \rho)=u_{t}(t-\tau \rho) & \forall t \in \mathbb{R}^{+}, \forall \rho \in(0,1) \\ z_{0}(\rho)=z(0, \rho)=f_{0}(-\tau \rho) & \forall \rho \in] 0,1[ \end{cases}
$$

Then, we have

$$
\begin{cases}\eta_{t}(t, s)+\eta_{s}(t, s)=u_{t}(t) & \forall t, s \in \mathbb{R}^{+}  \tag{2.14}\\ \eta(t, 0)=0 & \forall t \in \mathbb{R}^{+}\end{cases}
$$

and

$$
\begin{cases}\tau z_{t}(t, \rho)+z_{\rho}(t, \rho)=0 & \forall t \in \mathbb{R}^{+}, \forall \rho \in(0,1)  \tag{2.15}\\ z(t, 0)=u^{\prime}(t) & \forall t \in \mathbb{R}^{+}\end{cases}
$$

By combining (1.2) and $(2.13)$, we obtain the following equation:
$u^{\prime \prime}-\left(\mu I d-\int_{0}^{+\infty} h(s) d s\right) \Delta u-(\lambda+\mu) \nabla \operatorname{div} u-\int_{0}^{+\infty} h(s) \Delta \eta d s+k z(t, 1)=0$ in $\Omega \times \mathbb{R}^{+}$
where

$$
I d=\left(\begin{array}{lll}
1 & 0 & 0  \tag{2.17}\\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right)
$$

Let the Hilbert spaces $L_{h}\left(\mathbb{R}^{+},\left(H_{0}^{1}(\Omega)\right)^{3}\right)$ defined by

$$
\left.L_{h}\left(\mathbb{R}^{+},\left(H_{0}^{1}(\Omega)\right)^{3}\right)\right)=\left\{v=\left(v_{1}, v_{2}, v_{3}\right)^{T}: \mathbb{R}^{+} \rightarrow\left(H_{0}^{1}(\Omega)\right)^{3}, \int_{0}^{+\infty} h_{i}(s)\left\|\nabla v_{i}(s)\right\|^{2} d s<+\infty\right\}
$$

supplemented with the inner product

$$
\langle v, w\rangle_{L_{h}}=\sum_{i=1}^{3} \int_{0}^{+\infty} h_{i}(s) \int_{\Omega} \nabla v_{i}(s) \cdot \nabla w_{i}(s) d x d s
$$

for some $w=\left(w_{1}, w_{2}, w_{3}\right)^{T}$ and

$$
L^{2}(] 0,1\left[, L^{2}(\Omega)\right)=\{v:] 0,1\left[\rightarrow L^{2}(\Omega), \int_{0}^{1}\|v(\rho)\|^{2} d \rho<+\infty\right\}
$$

endowed with the inner product

$$
\langle v, w\rangle_{L^{2}\left(0,1\left[, L^{2}(\Omega)\right)\right.}=\int_{0}^{1} \int_{\Omega} v(\rho) \cdot w(\rho) d x d \rho .
$$

Next, we will rewrite the system (1.2)-1.3) in the following related system:

$$
\left\{\begin{array}{l}
\mathcal{U}_{t}(t)=\mathcal{A} \mathcal{U}(t) \quad \forall t>0  \tag{2.18}\\
\mathcal{U}(0)=\mathcal{U}_{0}
\end{array}\right.
$$

where $\mathcal{U}=\left(u, u_{t}, \eta, z\right)^{T}, \mathcal{U}_{0}=\left(u_{0}, u_{1}, \eta_{0}, z_{0}\right)^{T} \in \mathcal{H}$

$$
\mathcal{H}=H_{0}^{1}(\Omega) \times\left(L^{2}(\Omega)\right) \times L_{g}\left(\mathbb{R}^{+}, H_{0}^{1}(\Omega)\right) \times L^{2}(] 0,1\left[, L^{2}(\Omega)\right) .
$$

The operator $\mathcal{A}$ is linear and given by

$$
\mathcal{A}=\left(\begin{array}{cccc}
0 & 1 & 0 & 0  \tag{2.19}\\
\Delta_{e}-\left(\int_{0}^{+\infty} h(s) d s\right) \Delta & 0 & \int_{0}^{+\infty} h(s) \Delta d s & -\mu \\
0 & 1 & -\partial_{s} & 0 \\
0 & 0 & 0 & -\frac{1}{\tau} \partial_{\rho}
\end{array}\right)
$$

The domain $D(\mathcal{A})$ of $\mathcal{A}$ is given by

$$
D(\mathcal{A})=\left\{W=\left(w_{1}, w_{2}, w_{3}, w_{4}\right)^{T} \in \mathcal{H}, \mathcal{A} W \in \mathcal{H}, w_{3}(0)=0 \text { and } w_{4}(0)=w_{2}\right\} .
$$

The well-posedness and uniqueness of the problem 2.18 is given in.

Theorem 2.1. Let the assumption (A1) and (A2) hold. Then, the system (2.18) has a unique weak solution for any $\mathcal{U}_{0} \in \mathcal{H}$, such that

$$
\mathcal{U} \in C\left(\mathbb{R}^{+}, \mathcal{H}\right)
$$

If $\mathcal{U} \in D(\mathcal{A})$, then the solution of 2.18 satisfies (classical solution)

$$
\mathcal{U} \in C^{1}\left(\mathbb{R}^{+}, \mathcal{H}\right) \cap C\left(\mathbb{R}^{+}, D(\mathcal{A})\right)
$$

Proof. We prove that $\mathcal{A}: D(\mathcal{A}) \rightarrow \mathcal{H}$ is a maximal monotone operator; that is, $\mathcal{A}$ is dissipative and $I d-\mathcal{A}$ is surjective. Indeed, a simple calculation implies that, for any $V=\left(v_{1}, v_{2}, v_{3}, v_{4}\right)^{T} \in D(\mathcal{A})$,

$$
\begin{align*}
\langle\mathcal{A} V, V\rangle_{\mathcal{H}}= & \sum_{i=1}^{3}\left\langle\Delta_{e} v_{1}^{i}-\int_{0}^{+\infty} h_{i}(s) \Delta v_{3}^{i} d s-k v_{4}^{i}(1), v_{2}^{i}\right\rangle+(\lambda+\mu)\left\langle\operatorname{div} v_{2}, \operatorname{div} v_{1}\right\rangle \\
& +\sum_{i=1}^{3}\left(\mu-\alpha_{i}\right)\left\langle\nabla v_{2}^{i}, \nabla v_{1}^{i}\right\rangle+\left\langle-\frac{\partial v_{3}}{\partial s}+v_{2}, v_{3}\right\rangle_{L_{g}^{2}}+\tau|\mu|\left\langle-\frac{1}{\tau} \frac{\partial v_{4}}{\partial \rho}, v_{4}\right\rangle_{L^{2}(] 0,1[, H)} \\
\leq & \frac{1}{2} \sum_{i=1}^{3} \int_{0}^{+\infty} h_{i}^{\prime}(s) \int_{\Omega}\left|\nabla v_{3}^{i}\right|^{2} d x d s \leq 0 \tag{2.20}
\end{align*}
$$

since $g_{i}$ nonincreasing. This implies that $\mathcal{A}$ is dissipative. On the other hand, we prove that $I d-\mathcal{A}$ is surjective. Indeed, let $F=\left(f_{1}, f_{2}, f_{3}, f_{4}\right)^{T} \in \mathcal{H}$ we show that there exists $V=\left(v_{1}, v_{2}, v_{3}, v_{4}\right)^{T} \in D(\mathcal{A})$ satisfying

$$
\begin{equation*}
(I d-\mathcal{A}) V=F \tag{2.21}
\end{equation*}
$$

This is equivalent to

$$
\left\{\begin{array}{l}
v_{2}=v_{1}-f_{1}  \tag{2.22}\\
v_{3}+\frac{\partial v_{3}}{\partial s}=f_{3}+v_{1}-f_{1}, \\
v_{4}+\frac{1}{\tau} \frac{\partial v_{4}}{\partial \rho}=f_{4} \\
\left(\Delta_{e}+(1+|k|) I d\right) v_{1}+\int_{0}^{+\infty} h(s) \Delta v_{3} d s=(1+|k|) f_{1}+f_{2}-k v_{4}(1)
\end{array}\right.
$$

Noting that the second equation in 2.22$)_{2}$ with $v_{3}(0)=0$ admits a unique solution

$$
\begin{equation*}
v_{3}=\left({ }_{0}^{s} e^{y}\left(f_{3}(y)+v_{1}-f_{1}\right) d y\right) e^{-s} \tag{2.23}
\end{equation*}
$$

Eq. 2.22$)_{3}$ with $v_{4}(0)=v_{2}=v_{1}-f_{1}$ has a unique solution

$$
\begin{equation*}
v_{4}=\left(v_{1}-f_{1}+\tau \int_{0}^{\rho} f_{4}(y) e^{\tau y} d y\right) e^{-\tau \rho} \tag{2.24}
\end{equation*}
$$

By $(2.23$ and $(2.24)$ the $\mathrm{Eq}(2.224$ becomes

$$
\begin{equation*}
\left.\left(l \Delta_{e}+(1+|k|)+e^{-\tau} k\right) I d\right) v_{1}=\widetilde{f} \tag{2.25}
\end{equation*}
$$

where

$$
l=\int_{0}^{+\infty} h(s) e^{-s}\left(\int_{0}^{s} e^{y} d y\right) d s=1-\int_{0}^{+\infty} h(s) e^{-s} d s
$$

and
$\widetilde{f}=f_{2}+\left(1+|k|+e^{-\tau} k\right) f_{1}-\int_{0}^{s} g(s) e^{-s}\left(\int_{0}^{s} e^{y} \Delta\left(f_{3}(y)-f_{1}\right) d y\right) d s-\tau k e^{-\tau} \int_{0}^{1} f_{4}(y) e^{\tau y} d y$. We have just to prove that 2.25 has a solution $w_{1} \in H^{2}(\Omega) \cap H_{0}^{1}(\Omega)$ and replace in 2.23 , (2.24) and the first equation in $(2.22)$ to obtain $V \in D(\mathcal{A})$ satisfying (2.21). So we multiply 2.25 by a test function $\varphi_{1} \in\left(H_{0}^{1}(\Omega)\right)^{3}$ and we integrate by parts, obtaining the following variational formulation of 2.25 :

$$
\begin{equation*}
a\left(v_{1}, \varphi_{1}\right)=L\left(\varphi_{1}\right) \quad \forall \varphi_{1} \in\left(H_{0}^{1}(\Omega)\right)^{3} \tag{2.26}
\end{equation*}
$$

where

$$
\begin{align*}
a\left(v_{1}, \varphi_{1}\right)= & \int_{\Omega}\left(v_{1} \cdot \varphi_{1}+\sum_{i=1}^{3}\left(\mu-\alpha_{i}\right) \nabla v_{1} \cdot \nabla \varphi_{1}+(\lambda+\mu) \operatorname{div} v_{1} \cdot \operatorname{div} \varphi_{1}\right) d x  \tag{2.27}\\
& \left.\left.+\int_{\Omega}(1+|k|)+e^{-\tau} k\right) I d\right) v_{1} \cdot \varphi_{1} d x
\end{align*}
$$

and

$$
\begin{align*}
L\left(\varphi_{1}\right)= & \int_{\Omega}\left(f_{2}+\left(1+|k|+e^{-\tau} k\right) f_{1}-\tau k e^{-\tau} \int_{0}^{1} f_{4}(y) e^{\tau y} d y\right) \varphi_{1} d x  \tag{2.28}\\
& +\int_{\Omega} \int_{0}^{s} h(s) e^{-s}\left(\int_{0}^{s} e^{y} \nabla\left(f_{3}(y)-f_{1}\right) d y\right) d s . \nabla \varphi_{1} d x
\end{align*}
$$

It is clear that $a$ is a bilinear and continuous form on $\left(H_{0}^{1}(\Omega)\right)^{3} \times\left(H_{0}^{1}(\Omega)\right)^{3}$, and $L$ is a linear and continuous form on $\left(H_{0}^{1}(\Omega)\right)^{3}$. On the other hand, 1.1 and (2.11) imply that there exists a positive constant $a_{0}$ such that

$$
a\left(v_{1}, v_{1}\right) \geq a_{0}\left\|v_{1}\right\|_{\left(H_{0}^{1}(\Omega)\right)^{3}}, \quad \forall v_{1} \in\left(H_{0}^{1}(\Omega)\right)^{3}
$$

which implies that $a$ is coercive. Therefore, using the Lax-Milgram Theorem, we conclude that (2.26) has a unique solution $v_{1} \in\left(H_{0}^{1}(\Omega)\right)^{3}$. We then conclude that the solution $v_{1}$ of (2.26) belongs into $\left(H^{2}(\Omega) \cap H_{0}^{1}(\Omega)\right)^{3}$ and satisfies (2.25. Consequently, using (2.23) and (2.24), we deduce that (2.21) has a unique solution $V \in D(\mathcal{A})$, this ensured that $I d-\mathcal{A}$ is surjective. Eqs. 2.20 and 2.21 inform us that $-\mathcal{A}$ is maximal monotone operator. By Lummer-Phillips theorem (see [14]), we deduce that $\mathcal{A}$ is an infinitesimal generator of a linear $C_{0}$-semigroup on $\mathcal{H}$.

## 3. Stability Results

We now define the classical energy of any weak solution $u$ of (1.2)-(1.3) at time $t$ as

$$
E_{u}(t)=\frac{1}{2} \int_{\Omega}\left(\sum_{i=1}^{3}\left(\mu-\alpha_{i}\right)\left|\nabla u_{i}\right|^{2}+(\lambda+\mu)|\operatorname{div} u|^{2}+\left|u^{\prime}\right|^{2}\right) d x+\frac{\tau|k|}{2} \int_{\Omega} \int_{0}^{1} z^{2}(t, \rho) d \rho d x
$$

The modifed energy functional of the weak solution $u$ is defined by

$$
\begin{equation*}
E(t)=E_{u}(t)+\frac{1}{2} h \circ \nabla \eta, \quad \forall t \in \mathbb{R}^{+} \tag{3.29}
\end{equation*}
$$

where

$$
\begin{equation*}
h \circ \nabla \eta=\sum_{i=1}^{3} \int_{0}^{+\infty} g_{i}(s) \int_{\Omega}\left|\nabla u_{i}(x, t)-u_{i}(x, t-s)\right|^{2} d x d s \tag{3.30}
\end{equation*}
$$

The next theorem is our main stability result.

Theorem 3.1. Assume that (A1), (A2) and (1.1) hold. Then there exists a positive constant $\delta_{0}$ independent of $k$ such that, if

$$
|k|<\delta_{0}
$$

then, for any $\mathcal{U}_{0} \in \mathcal{H}$, there exist a positive constants $\delta_{1}$ and $\delta_{2}$, such that the solution of (2.18) satisfies

$$
\begin{equation*}
E(t) \leq \delta_{2} e^{-\delta_{1} t} \quad \forall t \in \mathbb{R}^{+} \tag{3.31}
\end{equation*}
$$

The proof of Theorem 3.1 based on several Lemmas. The next Lemma means that our problem is dissipatif.

Lemma 3.1. The functional (3.29) satisfies, along the solution $u$ of (1.2)-(1.3),

$$
\begin{equation*}
E^{\prime}(t) \leq \frac{1}{2} h^{\prime} \circ \nabla \eta+|k| \int_{\Omega}\left|u^{\prime}(t)\right|^{2} d x, \quad \forall t \in \mathbb{R}^{+} . \tag{3.32}
\end{equation*}
$$

Proof. The multiplication of 1.2 by $u^{\prime}$, integrating by parts over $\Omega$, we get easily (3.32).

In order to introduce an appropriate Lyapunov functional, we introduce the estimates.

Lemma 3.2. The functional

$$
\begin{equation*}
\phi(t)=\int_{\Omega} u u^{\prime} d x, \quad \forall t \in \mathbb{R}^{+} \tag{3.33}
\end{equation*}
$$

satisfies for any $\varepsilon>0$

$$
\begin{align*}
\phi^{\prime}(t) \leq & \int_{\Omega}\left|u^{\prime}\right|^{2} d x-\sum_{i=1}^{3}\left(\mu-\varepsilon-\alpha_{i}\right) \int_{\Omega}\left|\nabla u_{i}\right|^{2} d x  \tag{3.34}\\
& -(\lambda+\mu) \int_{\Omega}|\operatorname{div} u|^{2} d x-k \int_{\Omega} z(t, 1) \cdot u d x+\frac{c_{1}}{4 \varepsilon} h \circ \nabla \eta .
\end{align*}
$$

Proof. By differentiating (3.33) and using (2.16), and (3.30), we obtain

$$
\begin{align*}
\phi^{\prime}(t)= & \int_{\Omega}\left|u^{\prime}\right|^{2} d x-\sum_{i=1}^{3}\left(\mu-\alpha_{i}\right) \int_{\Omega}\left|\nabla u_{i}\right|^{2} d x-(\lambda+\mu) \int_{\Omega}|\operatorname{div} u|^{2} d x  \tag{3.35}\\
& +|k| \int_{\Omega} z(t, 1) \cdot u d x-\sum_{i=1}^{3} \int_{0}^{+\infty} h_{i}(s) \int_{\Omega} \nabla u_{i} . \nabla \eta_{i} d x d s
\end{align*}
$$

By using Cauchy-Schwarz and Young's inequalities for the last term of (3.35), we obtain

$$
\begin{equation*}
-\int_{0}^{+\infty} h(s) \int_{\Omega} \nabla u . \nabla \eta d x d s \leq \quad \varepsilon \int_{\Omega}|\nabla u|^{2} d x+\frac{c_{1}}{4 \varepsilon} h \circ \nabla \eta . \tag{3.36}
\end{equation*}
$$

Inserting the last inequalities in (3.35), we obtain (3.34).

Lemma 3.3. The functional

$$
\begin{equation*}
\psi(t)=-\sum_{i=1}^{3} \int_{0}^{+\infty} h_{i}(s) \int_{\Omega} u_{i}^{\prime} \cdot \eta_{i} d x d s, \quad \forall t \in \mathbb{R}^{+} \tag{3.37}
\end{equation*}
$$

satisfies for any $\varepsilon>0$

$$
\begin{align*}
\psi^{\prime}(t) \leq & -\sum_{i=1}^{3}\left(\alpha_{i}-\varepsilon\right) \int_{\Omega}\left|u_{i}^{\prime}\right|^{2} d x+\varepsilon \int_{\Omega}\left(|\nabla u|^{2}+|\operatorname{div} u|^{2}\right) d x \\
& +\frac{c_{1}}{\varepsilon} h \circ \nabla \eta-\frac{c_{2}}{\varepsilon} h^{\prime} \circ \nabla \eta+k \int_{\Omega} z(t, 1) .\left(\int_{0}^{+\infty} h(s) \eta d s\right) d x . \tag{3.38}
\end{align*}
$$

Proof. $\quad$ Multiplying (2.16) by $\int_{0}^{+\infty} h(s) \eta(t, s) d s$ and integrating over $\Omega$, we get

$$
\begin{align*}
0= & \sum_{i=1}^{3} \int_{0}^{+\infty} h_{i}(s) \int_{\Omega} u_{i}^{\prime \prime} \cdot \eta_{i} d x d s \\
& -\sum_{i=1}^{3} \int_{\Omega}\left(\mu \Delta u_{i}+(\lambda+\mu) \nabla \operatorname{div} u_{i}\right)\left(\int_{0}^{+\infty} h_{i}(s) \eta_{i} d s\right) d x  \tag{3.39}\\
& +\sum_{i=1}^{3} \int_{\Omega}\left(\int_{0}^{+\infty} h_{i}(s) \Delta \eta_{i} d s\right)\left(\int_{0}^{+\infty} h_{i}(s) \eta_{i} d s\right) d x
\end{align*}
$$

By using the fact that, $\partial_{t} \eta(t, s)=-\partial_{s} \eta(t, s)+u^{\prime}(t)$, we find

$$
\begin{align*}
& \sum_{i=1}^{3} \int_{0}^{+\infty} h_{i}(s) \int_{\Omega} u_{i}^{\prime \prime} \eta_{i} d x d s \\
& =\sum_{i=1}^{3}\left(\frac{\partial}{\partial t} \int_{0}^{+\infty} h_{i}(s) \int_{\Omega} u_{i}^{\prime} \eta_{i} d x d s-\int_{0}^{+\infty} h_{i}(s) \int_{\Omega} u_{i} \eta_{i}^{\prime} d x d s\right)  \tag{3.40}\\
& =-\psi^{\prime}(t)-\sum_{i=1}^{3} \alpha_{i} \int_{\Omega}\left|u_{i}\right|^{2} d x+\sum_{i=1}^{3} \int_{0}^{+\infty} h_{i}(s) \int_{\Omega} u_{i} \partial_{s} \eta d x d s .
\end{align*}
$$

By the fact that $\lim _{s \rightarrow+\infty} h_{i}(s)=0$ and $\eta_{i}(t, 0)=0$, integration with respect to $s$, we obtain

$$
\begin{equation*}
\sum_{i=1}^{3} \int_{0}^{+\infty} h_{i}(s) \int_{\Omega} u_{i}^{\prime \prime} \eta_{i} d x d s=-\psi^{\prime}(t)-\sum_{i=1}^{3} \alpha_{i} \int_{\Omega}\left|u_{i}^{\prime}\right|^{2}+\sum_{i=1}^{3} \int_{\Omega} u_{i}^{\prime}\left(\int_{0}^{+\infty} h_{i}(s) \partial_{s} \eta_{i} d s\right) d x \tag{3.41}
\end{equation*}
$$

Exploiting (3.39) and (3.41), we deduce that

$$
\begin{align*}
\psi^{\prime}(t)= & -\sum_{i=1}^{3} \alpha_{i} \int_{\Omega}\left|u_{i}\right|^{2}+k \sum_{i=1}^{3} \int_{\Omega} z(t, 1) \cdot\left(\int_{0}^{+\infty} h_{i}(s) \eta_{i} d s\right) d x \\
& -\sum_{i=1}^{3} \int_{\Omega} u_{i}^{\prime}\left(\int_{0}^{+\infty} h_{i}^{\prime}(s) \eta_{i} d s\right) d x  \tag{3.42}\\
& +\sum_{i=1}^{3} \int_{\Omega}\left(\left(\mu-\alpha_{i}\right) \nabla u_{i}+(\lambda+\mu) \operatorname{div} u_{i}\right) \int_{0}^{+\infty} h_{i}(s) \nabla \eta_{i} d s d x \\
& +\sum_{i=1}^{3} \int_{\Omega}\left(\int_{0}^{+\infty} h_{i}(s) \nabla \eta_{i} d s\right) \cdot\left(\int_{0}^{+\infty} h_{i}(s) \nabla \eta_{i} d s\right) d x
\end{align*}
$$

Thanks to Cauchy-Schwarz and Young's inequalities to get

$$
\begin{align*}
& -\sum_{i=1}^{3} \int_{\Omega} u_{i}^{\prime}\left(\int_{0}^{+\infty} h_{i}^{\prime}(s) \eta_{i} d s\right) d x \leq \varepsilon \sum_{i=1}^{3} \int_{\Omega}\left|u_{i}^{\prime}\right|^{2} d x-\sum_{i=1}^{3} \frac{h_{i}(0)}{4 \varepsilon} h_{i}^{\prime} \circ \nabla \eta_{i} .  \tag{3.43}\\
& \sum_{i=1}^{3} \int_{\Omega} \nabla u_{i} \int_{0}^{+\infty} h_{i}(s) \nabla \eta_{i} d s d x \leq \varepsilon \sum_{i=1}^{3} \int_{\Omega}\left|\nabla u_{i}\right|^{2} d x+\sum_{i=1}^{3} \frac{\alpha_{i}\left(1-\alpha_{i}\right)^{2}}{4 \varepsilon} h_{i} \circ \nabla \eta_{i}
\end{align*}
$$

and

$$
\sum_{i=1}^{3} \int_{\Omega}\left(\int_{0}^{+\infty} h_{i}(s) \nabla \eta_{i} d s\right)^{2} d x \leq \alpha_{i} h_{i} \circ \nabla \eta_{i}
$$

Then, the proof is completes.

Lemma 3.4. Let us define functional

$$
\begin{equation*}
I(t)=\int_{0}^{L} \int_{\Omega} e^{-2 \tau \rho} z(t, \rho) d \rho d x, \quad \forall t \in \mathbb{R}^{+} \tag{3.44}
\end{equation*}
$$

satisfy

$$
\begin{equation*}
I^{\prime}(t) \leq-2 e^{-2 \tau} \int_{\Omega} \int_{0}^{1}|z(t, \rho)|^{2} d \rho d x+\frac{1}{\tau} \int_{\Omega}\left|u^{\prime}\right|^{2} d x-\frac{e^{-2 \tau}}{\tau} \int_{\Omega}|z(t, 1)|^{2} d x \tag{3.45}
\end{equation*}
$$

Proof. By Eq. 2.15), the derivative of $I$ gives

$$
\begin{align*}
I^{\prime}(t) & =2 \int_{0}^{1} e^{-2 \tau \rho}\left\langle z^{\prime}(t, \rho), z(t, \rho)\right\rangle d \rho \\
& =-\frac{2}{\tau} \int_{0}^{1} e^{-2 \tau \rho}\left\langle\partial_{\rho} z(t, \rho), z(t, \rho)\right\rangle d \rho  \tag{3.46}\\
& =-\frac{1}{\tau} \int_{0}^{1} e^{-2 \tau \rho} \frac{\partial}{\partial_{\rho}}\|z(t, \rho)\|^{2} d \rho .
\end{align*}
$$

Then by the fact that $z(t, 0)=u^{\prime}(t)$, we have

$$
I^{\prime}(t)=-2 \int_{\Omega} \int_{0}^{1} e^{-2 \tau \rho}|z(t, \rho)|^{2} d \rho d x+\frac{1}{\tau} \int_{\Omega}\left|u^{\prime}\right|^{2} d x-\frac{e^{-2 \tau}}{\tau} \int_{\Omega}|z(t, 1)|^{2} d x
$$

which leads our result, since $-e^{-2 \tau_{1} \rho} \leq-e^{-2 \tau_{1}}$, for any $\rho \in(0,1)$.

Now, we are ready to prove our main stability results (3.31).
Proof Let $L(t)=N_{1} E(t)+N_{2} \phi(t)+\psi(t)+I(t)$, for $N_{1}, N_{2}>0$. By definition of $\varphi, \psi, I$ and $E$, there exist two constants $d_{1}$ and $d_{2}$ such that

$$
\begin{equation*}
d_{1} E(t) \leq L(t) \leq d_{2} E(t) \tag{3.47}
\end{equation*}
$$

On the other hand, combining (3.32), (3.33), (3.37) and (3.45), we obtain

$$
\begin{align*}
L^{\prime}(t) \leq & \left(\frac{N_{1}}{2}-\frac{c_{1}}{\varepsilon}\right) h^{\prime} \circ \nabla \eta+\left(\frac{N_{2} c}{4 \varepsilon}+\frac{c_{1}}{\varepsilon}\right) h \circ \nabla \eta-\sum_{i=1}^{3}\left(\alpha_{i}-\varepsilon-N_{2}-\frac{1}{\tau}\right) \int_{\Omega}\left|u_{i}^{\prime}\right|^{2} d x \\
& -(\lambda+\mu) \int_{\Omega}|\operatorname{div} u|^{2} d x-\sum_{i=1}^{3}\left(N_{2}\left(\mu-\varepsilon-\alpha_{i}\right)-(1+\widehat{c}) \varepsilon\right) \int_{\Omega}\left|\nabla u_{i}\right|^{2} d x \\
& -2 e^{-2 \tau} \int_{\Omega} \int_{0}^{1}|z(t, \rho)|^{2} d \rho d x-\frac{e^{-2 \tau}}{\tau} \int_{\Omega}|z(t, 1)|^{2} d x \\
& +k\left\langle z(t, 1),-N_{2} u(t)+\int_{0}^{+\infty} h(s) \eta d s\right\rangle \tag{3.48}
\end{align*}
$$

where $\widehat{c}>0$ satisfies

$$
\int_{\Omega}|\operatorname{div} u|^{2} d x \leq \widehat{c} \int_{\Omega}|\nabla u|^{2} d x
$$

Next, the use of Cauchy-Schwarz and Young's inequalities, we obtain

$$
\begin{align*}
& k\left\langle z(t, 1),-N_{2} u(t)+\int_{0}^{+\infty} h(s) \eta d s\right\rangle \\
& \leq \varepsilon_{1}\|z(t, 1)\|^{2}+\frac{k^{2}}{4 \varepsilon_{1}}\left(N_{2}\|u(t)\|+\int_{0}^{+\infty} h(s)\|\eta(t, s)\| d s\right)^{2}  \tag{3.49}\\
& \leq \varepsilon_{1}\|z(t, 1)\|^{2}+\frac{k^{2} c}{4 \varepsilon_{1}}\left(N_{2}^{2}\|\nabla u(t)\|^{2}+\alpha_{i} \int_{0}^{+\infty} h(s)\|\nabla \eta(t, s)\|^{2} d s\right) \\
& \leq \varepsilon_{1}\|z(t, 1)\|^{2}+\varepsilon_{1} k^{2} c_{6}\left(\|\nabla u(t)\|^{2}+\alpha_{i} \int_{0}^{+\infty} h(s)\|\nabla \eta(t, s)\|^{2} d s\right)
\end{align*}
$$

where $c_{6}=\max \left\{N_{2}^{2}, \alpha_{i}\right\}$. We now choose $0<\varepsilon<\mu-\max _{1 \leq i \leq 3}\left\{\alpha_{i}\right\}$ and $0<\varepsilon_{1}<$ $\min _{1 \leq i \leq 3}\left\{\alpha_{i}\right\}$. Next, we choose $N_{2}$ and $\varepsilon_{2}$ such that $0<N_{2}<\min _{1 \leq i \leq 3}\left\{\alpha_{i}\right\}-\varepsilon_{1}-\frac{1}{\tau}$ and $0<\varepsilon_{2}<\frac{N_{2}}{1+\bar{c}}\left(\mu-\max _{1 \leq i \leq 3}\left\{\alpha_{i}\right\}-\varepsilon\right)$. These choices imply that $\alpha_{i}-\varepsilon_{1}-N_{2}$ and $\left(N_{2}\left(\mu-\varepsilon-\alpha_{i}\right)-(1+\widehat{c}) \varepsilon_{2}\right)$ are positive constants. Then, we obtain, for some $\beta, c_{3}, c_{4}>0$,

$$
\begin{equation*}
L^{\prime}(t) \leq-\beta E(t)+\left(\frac{N_{1}}{2}-c_{3}\right) h^{\prime} \circ \nabla \eta+c_{4} h \circ \nabla \eta, \quad \forall t \in \mathbb{R}^{+} . \tag{3.50}
\end{equation*}
$$

Finally, we can choose $N_{1}$ large enough so that $\frac{N_{1}}{2}-c_{3} \geq 0$

$$
\begin{equation*}
L^{\prime}(t) \leq-\beta E(t)+c_{4} h \circ \nabla \eta, \quad \forall t \in \mathbb{R}^{+} . \tag{3.51}
\end{equation*}
$$

If (2.12) is satisfied, for any $i=1,2,3$, then

$$
\begin{equation*}
h_{i} \circ \nabla \eta_{i} \leq-\frac{1}{\delta_{i}} h_{i}^{\prime} \circ \nabla \eta_{i} . \tag{3.52}
\end{equation*}
$$

Combing (3.53) and (3.52) imply that

$$
\begin{equation*}
L^{\prime}(t) \leq-\beta E(t)-c_{5} h^{\prime} \circ \nabla \eta, \quad \forall t \in \mathbb{R}^{+} . \tag{3.53}
\end{equation*}
$$

where $c_{5}=c_{4} \max \left\{\delta_{i}\right\}$
Let $F=L+c_{5} E$. Using (3.32), we get

$$
\begin{equation*}
F^{\prime}(t) \leq-\beta E(t) \quad \forall t \in \mathbb{R}^{+} . \tag{3.54}
\end{equation*}
$$

Because $L \sim E$, then $F \sim E$. Therefore, (3.54) implies that

$$
F^{\prime}(t) \leq-c^{\prime} F(t) \quad \forall t \in \mathbb{R}^{+}
$$

for some $c^{\prime}>0$. By integrating this differential inequality, we get

$$
F(t) \leq F(0) e^{-c^{\prime} t}, \quad \forall t \in \mathbb{R}^{+}
$$

Thus, thanks to $F \sim E$, we get (3.31).

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