



## SOME RESULTS ON $\beta$ -KENMOTSU MANIFOLDS WITH A NON-SYMMETRIC NON-METRIC CONNECTION

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*Dedicated to the memory of the late Professor Krishan Lal Duggal(1929-2022)*

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**ABSTRACT.** The object of the present paper is to study some results on a  $\beta$ -Kenmotsu manifold with a non-symmetric non-metric connection. We obtain the condition for the manifold with a non-symmetric non-metric connection to be projectively flat and conformally flat. Also, it has been demonstrated that the manifold satisfying the condition  $\check{\mathcal{R}}^\dagger \cdot \check{\mathcal{S}}^\dagger = 0$  is an Einstein manifold. Further, by virtue of this result, we found the condition of Ricci soliton in  $\beta$ -Kenmotsu manifold to be expanding.

**Keywords:** Non-symmetric non-metric connection,  $\beta$ -Kenmotsu manifold, conformal curvature tensor, Ricci soliton, Einstein manifold, Ricci semi-symmetric.

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### 1. INTRODUCTION

K. Kenmotsu [14] studied a class of almost contact manifolds and identified it as a Kenmotsu manifold. The fundamental properties of local structure of these manifolds were studied by him [14]. Trans-Sasakian manifolds were introduced by J. A. Oubiña [16], which

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generalizes forms of Sasakian, Kenmotsu and cosymplectic manifolds. A trans-Sasakian manifold of type  $(0, 0)$ ,  $(\alpha, 0)$  and  $(0, \beta)$  are Cosymplectic,  $\alpha$ -Sasakian and  $\beta$ -Kenmotsu manifolds respectively, where  $\alpha, \beta$  are smooth functions. In particular, a trans-Sasakian manifold will be Kenmotsu and Sasakian manifold, if  $\alpha = 0, \beta = 1$  and  $\alpha = 1, \beta = 0$  respectively.  $\beta$ -Kenmotsu manifold provides a large variety of Kenmotsu manifolds. Recently, Kenmotsu manifolds have been studied by several authors (cf. [8, 6, 11, 13, 23, 24]).

On differentiable manifolds, A. Friedmann and J. A. Schouten [12] first proposed a semi-symmetric linear connection. On Riemannian manifolds, semi-symmetric metric connection was first systematically examined by K. Yano [25], which was further studied by authors, including S. Ahmad and S. I. Hussain [21], M. M. Tripathi [22] and others. Semi-symmetric non-metric connection was established in a Riemannian manifold by N. S. Agashe and M. R. Chafle [1]. In line with this, S. K. Chaubey et al. [2] introduced the notion of non-symmetric non-metric connection. It has been further studied in [4, 5, 7, 17, 18, 19].

A torsion tensor of a connection is a mapping  $\mathcal{T}' : \chi(\Omega) \times \chi(\Omega) \rightarrow \chi(\Omega)$  defined by

$$\mathcal{T}'(\mathcal{X}_1, \mathcal{X}_2) = \hat{\nabla}_{\mathcal{X}_1} \mathcal{X}_2 - \hat{\nabla}_{\mathcal{X}_2} \mathcal{X}_1 - [\mathcal{X}_1, \mathcal{X}_2]. \tag{1.1}$$

A connection  $\hat{\nabla}$  is symmetric if  $\mathcal{T}' = 0$  and it is non-symmetric if  $\mathcal{T}' \neq 0$ . The connection  $\check{\nabla}$  is metric if  $\check{\nabla}_{\mathcal{X}} \hat{g} = 0$  and it is non-metric if  $\check{\nabla}_{\mathcal{X}} \hat{g} \neq 0$ . It was further studied by several geometers [10, 9].

In a Riemannian manifold  $(\Omega^{2n+1}, \hat{g})$ ,  $\hat{g}$  is a Ricci soliton if

$$(\mathcal{L}_{\mathcal{V}} \hat{g})(\mathcal{X}_1, \mathcal{X}_2) + 2\mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_2) + 2\Theta \hat{g}(\mathcal{X}_1, \mathcal{X}_2) = 0, \tag{1.2}$$

$\forall \mathcal{X}_1, \mathcal{X}_2$  and  $\mathcal{V}$  on  $\Omega^{2n+1}$ , where  $\mathcal{L}_{\mathcal{V}}$  denote the Lie-derivative along the vector field  $\mathcal{V}$ ,  $\mathcal{S}^\dagger$  is Ricci tensor and  $\Theta$  is a constant. The Ricci soliton is shrinking, steady and expanding if  $\Theta < 0$ ,  $\Theta = 0$  and  $\Theta > 0$  respectively.

This paper is organized as follows: In Section 2, we present an informative introduction of  $\beta$ -Kenmotsu manifold. In Section 3, we define non-symmetric non-metric connection. In Section 4, we find the curvature tensor with non-symmetric non-metric connection. In Section 5, we investigate projectively and conformally flat  $\beta$ -Kenmotsu manifolds with defined connection. In Section 6, we show that the manifold with the defined connection satisfying the condition  $\check{\mathcal{R}}^\dagger \cdot \check{\mathcal{S}}^\dagger = 0$  is an Einstein manifold.

## 2. PRELIMINARIES

A smooth manifold  $\Omega^{2n+1}$  is almost contact metric [15] if it admits a  $(1, 1)$ -tensor field  $\hat{\varphi}$ , an associated vector field  $\hat{\zeta}$ , a 1-form  $\hat{\eta}$  and the Riemannian metric  $\hat{g}$  satisfying

$$\hat{\varphi}^2 \mathcal{X}_1 = -\mathcal{X}_1 + \hat{\eta}(\mathcal{X}_1) \hat{\zeta}, \quad \hat{\eta}(\hat{\zeta}) = 1, \quad \hat{\varphi}\hat{\zeta} = 0, \quad \hat{\eta}(\hat{\varphi}\mathcal{X}_1) = 0, \quad (2.3)$$

$$\hat{g}(\hat{\varphi}\mathcal{X}_1, \hat{\varphi}\mathcal{X}_2) = \hat{g}(\mathcal{X}_1, \mathcal{X}_2) - \hat{\eta}(\mathcal{X}_1) \hat{\eta}(\mathcal{X}_2), \quad \hat{g}(\mathcal{X}_1, \hat{\zeta}) = \hat{\eta}(\mathcal{X}_1), \quad (2.4)$$

for all  $\mathcal{X}_1, \mathcal{X}_2 \in \mathcal{T}'\Omega$ .

An almost contact metric manifold  $\Omega^{2n+1}$  is a  $\beta$ -Kenmotsu manifold [20] if and only if

$$(\hat{\nabla}_{\mathcal{X}_1} \hat{\varphi})\mathcal{X}_2 = \beta[\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2) \hat{\zeta} - \hat{\eta}(\mathcal{X}_2) \hat{\varphi}(\mathcal{X}_1)]. \quad (2.5)$$

From (2.5), we have

$$\hat{\nabla}_{\mathcal{X}_1} \hat{\zeta} = \beta[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1) \hat{\zeta}], \quad (2.6)$$

$$(\hat{\nabla}_{\mathcal{X}_1} \hat{\eta})\mathcal{X}_2 = \beta\hat{g}(\hat{\varphi}\mathcal{X}_1, \hat{\varphi}\mathcal{X}_2) = \beta[\hat{g}(\mathcal{X}_1, \mathcal{X}_2) - \hat{\eta}(\mathcal{X}_1) \hat{\eta}(\mathcal{X}_2)]. \quad (2.7)$$

Further, the curvature tensor  $\mathcal{R}^\dagger$ , Ricci tensor  $\mathcal{S}^\dagger$  and Ricci operator  $\mathcal{Q}^\dagger$  in  $\beta$ -Kenmotsu manifold with the Levi-Civita connection  $\hat{\nabla}$  satisfy [20].

$$\begin{aligned} \mathcal{R}^\dagger(\mathcal{X}_1, \mathcal{X}_2) \hat{\zeta} &= -\beta^2[\hat{\eta}(\mathcal{X}_2) \mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1) \mathcal{X}_2] + (\mathcal{X}_1\beta)[\mathcal{X}_2 - \hat{\eta}(\mathcal{X}_2) \hat{\zeta}] \\ &\quad - (\mathcal{X}_2\beta)[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1) \hat{\zeta}], \end{aligned} \quad (2.8)$$

$$\mathcal{R}^\dagger(\hat{\zeta}, \mathcal{X}_1) \mathcal{X}_2 = (\beta^2 + \hat{\zeta}\beta)[\hat{\eta}(\mathcal{X}_2) \mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_2) \hat{\zeta}], \quad (2.9)$$

$$\mathcal{R}^\dagger(\hat{\zeta}, \mathcal{X}_1) \hat{\zeta} = (\beta^2 + \hat{\zeta}\beta)[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1) \hat{\zeta}], \quad (2.10)$$

$$\mathcal{S}^\dagger(\mathcal{X}_1, \hat{\zeta}) = -(2n\beta^2 + \hat{\zeta}\beta)\hat{\eta}(\mathcal{X}_1) - (2n-1)(\mathcal{X}_1\beta), \quad (2.11)$$

$$\mathcal{S}^\dagger(\hat{\zeta}, \hat{\zeta}) = -(2n\beta^2 + \hat{\zeta}\beta), \quad (2.12)$$

$$\mathcal{Q}^\dagger \hat{\zeta} = -(2n\beta^2 + \hat{\zeta}\beta) \hat{\zeta} - (2n-1) \text{grad}\beta. \quad (2.13)$$

**Definition 2.1.** A  $\beta$ -Kenmotsu manifold  $\Omega^{2n+1}$  is known as a generalized  $\eta$ -Einstein manifold if its Ricci tensor  $\mathcal{S}^\dagger$  of type  $(0, 2)$  satisfies

$$\mathcal{S}^\dagger = \lambda_1 \hat{g} + \lambda_2 \hat{\eta} \otimes \hat{\eta} + \lambda_3 [\hat{\eta} \otimes \omega + \omega \otimes \hat{\eta}], \quad (2.14)$$

where,  $\lambda_1, \lambda_2$  and  $\lambda_3$  are smooth functions,  $\omega$  is a 1-form defined by  $\omega(\mathcal{X}_1) = \hat{g}(\mathcal{X}_1, \rho) \forall \mathcal{X}_1$ ,  $\rho$  and  $\hat{\zeta}$  are mutually orthogonal to each other.

**Definition 2.2.** *The projective curvature tensor of a  $(2n + 1)$ -dimensional  $\beta$ -Kenmotsu manifold  $\Omega$  is given by [4]*

$$\mathcal{P}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \mathcal{R}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{1}{2n}[\mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2]. \tag{2.15}$$

**Definition 2.3.** *The conformal curvature tensor  $\mathcal{C}^b$  of a  $(2n + 1)$ -dimensional  $\beta$ -Kenmotsu manifold  $\Omega$  [20] is given by*

$$\begin{aligned} \mathcal{C}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= \mathcal{R}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{1}{2n-1}[\mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2 \\ &\quad + \hat{g}(\mathcal{X}_2, \mathcal{X}_3)\mathcal{Q}^\dagger\mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_3)\mathcal{Q}^\dagger\mathcal{X}_2] \\ &\quad + \frac{k}{2n(2n-1)}[\hat{g}(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2] \end{aligned} \tag{2.16}$$

where  $\mathcal{R}^\dagger$ ,  $\mathcal{S}^\dagger$ ,  $\mathcal{Q}^\dagger$  and  $k$  is the curvature tensor, Ricci tensor, Ricci operator and scalar curvature respectively with  $\hat{\nabla}$ .

### 3. NON-SYMMETRIC NON-METRIC CONNECTION

The relation between non-symmetric non-metric connection  $\check{\nabla}$  and the Levi-Civita connection  $\hat{\nabla}$  [2, 3] is given as

$$\check{\nabla}_{\mathcal{X}_1}\mathcal{X}_2 = \hat{\nabla}_{\mathcal{X}_1}\mathcal{X}_2 + \hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta}, \tag{3.17}$$

which satisfies

$$\check{\mathcal{T}}'(\mathcal{X}_1, \mathcal{X}_2) = 2\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta} \tag{3.18}$$

and

$$(\check{\nabla}_{\mathcal{X}_1}\hat{g})(\mathcal{X}_2, \mathcal{X}_3) = -\hat{\eta}(\mathcal{X}_3)\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2) - \hat{\eta}(\mathcal{X}_2)\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_3) \tag{3.19}$$

for arbitrary vector fields  $\mathcal{X}_1$ ,  $\mathcal{X}_2$  and  $\mathcal{X}_3$ .

Let  $\Omega^{2n+1}$  be a  $\beta$ -Kenmotsu manifold with a non-symmetric non-metric connection  $\check{\nabla}$ , then

$$(\check{\nabla}_{\mathcal{X}_1}\hat{\varphi})(\mathcal{X}_2) = (\hat{\nabla}_{\mathcal{X}_1}\hat{\varphi})(\mathcal{X}_2) + \hat{g}(\hat{\varphi}\mathcal{X}_1, \hat{\varphi}\mathcal{X}_2)\hat{\zeta}, \tag{3.20}$$

$$(\check{\nabla}_{\mathcal{X}_1}\hat{\eta})(\mathcal{X}_2) = (\hat{\nabla}_{\mathcal{X}_1}\hat{\eta})(\mathcal{X}_2) - \hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2), \tag{3.21}$$

$$\check{\nabla}_{\mathcal{X}_1}\hat{\zeta} = \hat{\nabla}_{\mathcal{X}_1}\hat{\zeta}. \tag{3.22}$$

From (3.22), the following theorem yields:

**Theorem 3.1.** *The vector field  $\hat{\zeta}$  is invariant with respect to the connections  $\hat{\nabla}$  and  $\check{\nabla}$  [18].*

4. CURVATURE TENSOR ON A  $\beta$ -KENMOTSU MANIFOLD WITH NON-SYMMETRIC  
NON-METRIC CONNECTION

If  $\mathcal{R}^\dagger$  and  $\check{\mathcal{R}}^\dagger$  are the curvature tensors of connections  $\hat{\nabla}$  and  $\check{\nabla}$  respectively, we have

$$\check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \check{\nabla}_{\mathcal{X}_1}\check{\nabla}_{\mathcal{X}_2}\mathcal{X}_3 - \check{\nabla}_{\mathcal{X}_2}\check{\nabla}_{\mathcal{X}_1}\mathcal{X}_3 - \check{\nabla}_{[\mathcal{X}_1, \mathcal{X}_2]}\mathcal{X}_3, \quad (4.23)$$

from (2.5), (2.6) and (3.17), we have

$$\begin{aligned} \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= \mathcal{R}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + \beta[2\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\eta}(\mathcal{X}_3)\hat{\zeta} \\ &\quad + \hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2]. \end{aligned} \quad (4.24)$$

Putting  $\mathcal{X}_1 = e_i$  in (4.24) and summing over  $1 \leq i \leq (2n+1)$ , we get

$$\check{\mathcal{S}}^\dagger(\mathcal{X}_2, \mathcal{X}_3) = \mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_3) + 2n\beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_3), \quad (4.25)$$

$$\check{\mathcal{Q}}^\dagger(\mathcal{X}_2) = \mathcal{Q}^\dagger(\mathcal{X}_2) + 2n\beta(\hat{\varphi}\mathcal{X}_2). \quad (4.26)$$

Thus we state the following theorem:

**Theorem 4.1.** *In a  $\beta$ -Kenmotsu manifold, Ricci tensor and Ricci operator are defined by the equations (4.25) and (4.26) respectively endowed with  $\check{\nabla}$  and  $\hat{\nabla}$ .*

Contracting (4.25), it follows that

$$\check{k} = k. \quad (4.27)$$

Here  $\check{\mathcal{R}}^\dagger$ ,  $\check{\mathcal{S}}^\dagger$ ,  $\check{\mathcal{Q}}^\dagger$  and  $\check{k}$  is the curvature tensor, Ricci tensor, Ricci operator and scalar curvature respectively with  $\check{\nabla}$ .

Thus with the help of (4.27), we have following theorem:

**Theorem 4.2.** *If a  $\beta$ -Kenmotsu manifold  $\Omega^{2n+1}$  admits  $\check{\nabla}$ , then the scalar curvatures corresponding to  $\check{\nabla}$  and  $\hat{\nabla}$  coincide.*

By replacing  $\mathcal{X}_3 = \hat{\zeta}$ , in (4.24) and in view of (2.3), (2.4) and (2.8), we get

$$\begin{aligned} \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta} &= \beta^2(\hat{\eta}(\mathcal{X}_1)\mathcal{X}_2 - \hat{\eta}(\mathcal{X}_2)\mathcal{X}_1) + 2\beta\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta} \\ &\quad + (\mathcal{X}_1\beta)[\mathcal{X}_2 - \hat{\eta}(\mathcal{X}_2)\hat{\zeta}] - (\mathcal{X}_2\beta)[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\hat{\zeta}]. \end{aligned} \quad (4.28)$$

From (2.3), (2.9) and (4.24), we get

$$\check{\mathcal{R}}^\dagger(\hat{\zeta}, \mathcal{X}_2)\mathcal{X}_3 = (\beta^2 + \hat{\zeta}\beta)[\hat{\eta}(\mathcal{X}_3)\mathcal{X}_2 - \hat{g}(\mathcal{X}_2, \mathcal{X}_3)\hat{\zeta}] + \beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_3)\hat{\zeta}. \quad (4.29)$$

By using (2.3), (2.4), (2.10) and (4.24), we get

$$\begin{aligned} \check{\mathcal{R}}^\dagger(\hat{\zeta}, \mathcal{X}_1)\hat{\zeta} &= \mathcal{R}^\dagger(\hat{\zeta}, \mathcal{X}_1)\hat{\zeta} \\ &= (\beta^2 + \hat{\zeta}\beta)[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\hat{\zeta}]. \end{aligned} \tag{4.30}$$

Putting  $\mathcal{X}_3 = \hat{\zeta}$  in (4.25) and using (2.11), we get

$$\begin{aligned} \check{\mathcal{S}}^\dagger(\mathcal{X}_2, \hat{\zeta}) &= \mathcal{S}^\dagger(\mathcal{X}_2, \hat{\zeta}) \\ &= -(2n\beta^2 + \hat{\zeta}\beta)\hat{\eta}(\mathcal{X}_2) - (2n - 1)(\mathcal{X}_2\beta) \end{aligned} \tag{4.31}$$

and

$$\check{\mathcal{Q}}^\dagger(\mathcal{X}_2) = -(2n\beta^2 + \hat{\zeta}\beta)\hat{\zeta} - (2n - 1)grad\beta. \tag{4.32}$$

5. PROJECTIVELY CURVATURE TENSOR ON  $\beta$ -KENMOTSU MANIFOLD WITH NON-SYMMETRIC NON-METRIC CONNECTION

From Definition 2.2, we have

$$\check{\mathcal{P}}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 - \frac{1}{2n}[\check{\mathcal{S}}^\dagger(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2]. \tag{5.33}$$

Using (4.24), (4.25) in (5.33), we acquire

$$\check{\mathcal{P}}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 = \mathcal{P}^b(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 + 2\beta\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\eta}(\mathcal{X}_3)\hat{\zeta}. \tag{5.34}$$

Thus, we have the following results:

**Theorem 5.1.** *If a  $\beta$ -Kenmotsu manifold  $\Omega^{2n+1}$  admits  $\check{\nabla}$ , then the projective curvature tensors corresponding to  $\check{\nabla}$  and  $\hat{\nabla}$  are related by the equation (5.34).*

If  $\Omega^{2n+1}$  is  $\check{\mathcal{C}}^b$ -flat, then from Definition 2.3 we obtain

$$\begin{aligned} \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3 &= \frac{1}{2n - 1}[\check{\mathcal{S}}^\dagger(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2 \\ &\quad + \hat{g}(\mathcal{X}_2, \mathcal{X}_3)\check{\mathcal{Q}}^\dagger\mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_3)\check{\mathcal{Q}}^\dagger\mathcal{X}_2] \\ &\quad - \frac{\check{k}}{2n(2n - 1)}[\hat{g}(\mathcal{X}_2, \mathcal{X}_3)\mathcal{X}_1 - \hat{g}(\mathcal{X}_1, \mathcal{X}_3)\mathcal{X}_2]. \end{aligned} \tag{5.35}$$

Putting  $\mathcal{X}_3 = \hat{\zeta}$  in (5.35) and using (4.25), (4.26), (4.27) and (4.28), we have

$$\begin{aligned} \hat{\eta}(\mathcal{X}_2)\check{\mathcal{Q}}^\dagger\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\check{\mathcal{Q}}^\dagger\mathcal{X}_2 &= (\beta^2 + \hat{\zeta}\beta + \frac{k}{2n})[\hat{\eta}(\mathcal{X}_2)\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\mathcal{X}_2] \\ &\quad - (2n - 1)[(\mathcal{X}_1\beta)\hat{\eta}(\mathcal{X}_2) - (\mathcal{X}_2\beta)\hat{\eta}(\mathcal{X}_1)]\hat{\zeta} \\ &\quad + 2(2n - 1)\beta\hat{g}(\hat{\varphi}\mathcal{X}_1, \mathcal{X}_2)\hat{\zeta}. \end{aligned} \tag{5.36}$$

Again putting  $\mathcal{X}_2 = \hat{\zeta}$  in (5.36), we obtain

$$\begin{aligned} \check{Q}^\dagger \mathcal{X}_1 &= (\beta^2 + \hat{\zeta}\beta + \frac{k}{2n})\mathcal{X}_1 - ((2n+1)\beta^2 - (2n-3)\hat{\zeta}\beta + \frac{k}{2n})\hat{\eta}(\mathcal{X}_1)\hat{\zeta} \\ &\quad - (2n-1)((\mathcal{X}_1\beta)\hat{\zeta} + \hat{\eta}(\mathcal{X}_1)\text{grad}\beta). \end{aligned} \quad (5.37)$$

Hence

$$\begin{aligned} \check{S}^\dagger(\mathcal{X}_1, \mathcal{X}_2) &= (\beta^2 + \hat{\zeta}\beta + \frac{k}{2n})\hat{g}(\mathcal{X}_1, \mathcal{X}_2) - (2n-1)((\mathcal{X}_1\beta)\hat{\eta}(\mathcal{X}_2) + (\mathcal{X}_2\beta)\hat{\eta}(\mathcal{X}_1)) \\ &\quad - ((2n+1)\beta^2 - (2n-3)\hat{\zeta}\beta + \frac{k}{2n})\hat{\eta}(\mathcal{X}_1)\hat{\eta}(\mathcal{X}_2). \end{aligned} \quad (5.38)$$

Let  $\omega(\mathcal{X}_1) = \hat{g}(\mathcal{X}_1, \rho) = (\mathcal{X}_1\beta) = \hat{g}(\text{grad}\beta, \mathcal{X}_1) \forall \mathcal{X}_1$ . If  $\rho$  and  $\hat{\zeta}$  are orthogonal then  $\hat{\zeta}\beta = 0$  and (5.38) takes the form of (2.14). Therefore, we have the following theorem:

**Theorem 5.2.** *A conformally flat  $\beta$ -Kenmotsu manifold endowed with  $\check{\nabla}$  is a generalised  $\eta$ -Einstein manifold equipped with  $\check{\nabla}$ .*

#### 6. $\beta$ -KENMOTSU MANIFOLD SATISFYING $\check{\mathcal{R}}^\dagger \cdot \check{S}^\dagger = 0$

We consider a  $\beta$ -Kenmotsu manifold with  $\check{\nabla}$  connection satisfying

$$\check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2) \cdot \check{S}^\dagger = 0. \quad (6.39)$$

Therefore, we get

$$\check{S}^\dagger(\check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_3, \mathcal{X}_4) + \check{S}^\dagger(\mathcal{X}_3, \check{\mathcal{R}}^\dagger(\mathcal{X}_1, \mathcal{X}_2)\mathcal{X}_4) = 0. \quad (6.40)$$

Replacing  $\mathcal{X}_1$  by  $\hat{\zeta}$  in (6.40), it follows that

$$\check{S}^\dagger(\check{\mathcal{R}}^\dagger(\hat{\zeta}, \mathcal{X}_2)\mathcal{X}_3, \mathcal{X}_4) + \check{S}^\dagger(\mathcal{X}_3, \check{\mathcal{R}}^\dagger(\hat{\zeta}, \mathcal{X}_2)\mathcal{X}_4) = 0. \quad (6.41)$$

In view of (4.29), we have

$$\begin{aligned} &(\beta^2 + \hat{\zeta}\beta)[\hat{\eta}(\mathcal{X}_3)\check{S}^\dagger(\mathcal{X}_2, \mathcal{X}_4) - \hat{g}(\mathcal{X}_2, \mathcal{X}_3)\check{S}^\dagger(\hat{\zeta}, \mathcal{X}_4)] \\ &+ \beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_3)\check{S}^\dagger(\hat{\zeta}, \mathcal{X}_4) + (\beta^2 + \hat{\zeta}\beta)[\hat{\eta}(\mathcal{X}_4)\check{S}^\dagger(\mathcal{X}_3, \mathcal{X}_2) \\ &- \hat{g}(\mathcal{X}_2, \mathcal{X}_4)\check{S}^\dagger(\mathcal{X}_3, \hat{\zeta})] + \beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_4)\check{S}^\dagger(\mathcal{X}_3, \hat{\zeta}) = 0. \end{aligned} \quad (6.42)$$

Again replacing  $\mathcal{X}_3$  by  $\hat{\zeta}$  and using (2.3) and (4.31), we have

$$\begin{aligned} \check{S}^\dagger(\mathcal{X}_2, \mathcal{X}_4) &= - (2n\beta^2 + \hat{\zeta}\beta)\hat{g}(\mathcal{X}_2, \mathcal{X}_4) + (2n-1)((\mathcal{X}_2\beta)\hat{\eta}(\mathcal{X}_4) \\ &\quad - (\mathcal{X}_4\beta)\hat{\eta}(\mathcal{X}_2)) + 2n\beta\hat{g}(\hat{\varphi}\mathcal{X}_2, \mathcal{X}_4). \end{aligned} \quad (6.43)$$

Using (4.25), we have

$$\begin{aligned} \mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_4) &= -(2n\beta^2 + \hat{\zeta}\beta)\hat{g}(\mathcal{X}_2, \mathcal{X}_4) + (2n - 1)(\mathcal{X}_2\beta)\hat{\eta}(\mathcal{X}_4) \\ &\quad - (2n - 1)(\mathcal{X}_4\beta)\hat{\eta}(\mathcal{X}_2). \end{aligned} \tag{6.44}$$

Taking  $\mathcal{X}_4 = \hat{\zeta}$  in (6.44), we get

$$2(\mathcal{X}_2\beta) = (\hat{\zeta}\beta)\hat{\eta}(\mathcal{X}_2). \tag{6.45}$$

Again we take  $\mathcal{X}_2 = \hat{\zeta}$  in (6.45), we get

$$\hat{\zeta}\beta = 0. \tag{6.46}$$

Using (6.45) and (6.46) in (6.44), we have

$$\mathcal{S}^\dagger(\mathcal{X}_2, \mathcal{X}_4) = -2n\beta^2\hat{g}(\mathcal{X}_2, \mathcal{X}_4). \tag{6.47}$$

Thus we leads to the theorem:

**Theorem 6.1.** *A  $\beta$ -Kenmotsu manifold satisfying the condition  $\check{\mathcal{R}}^\dagger \cdot \check{\mathcal{S}}^\dagger = 0$  with  $\check{\nabla}$  is an Einstien manifold with  $\hat{\nabla}$ .*

A Ricci soliton in  $\beta$ -Kenmotsu manifold is defined by equation (1.2). Naturally, two cases appear corresponding to the vector field  $\mathcal{V} : \mathcal{V} \in Span\hat{\zeta}$  and  $\mathcal{V} \perp \hat{\zeta}$ . We consider only the case  $\mathcal{V} = \hat{\zeta}$ . The Ricci soliton  $(\hat{g}, \hat{\zeta}, \Theta)$  on a  $\beta$ -Kenmotsu manifold endowed with  $\check{\nabla}$  is defined as

$$(\check{\mathcal{L}}_{\hat{\zeta}}\hat{g})(\mathcal{X}_1, \mathcal{X}_2) + 2\check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_2) + 2\Theta\hat{g}(\mathcal{X}_1, \mathcal{X}_2) = 0. \tag{6.48}$$

Here

$$(\check{\mathcal{L}}_{\hat{\zeta}}\hat{g})(\mathcal{X}_1, \mathcal{X}_2) = (\check{\nabla}_{\hat{\zeta}}\hat{g})(\mathcal{X}_1, \mathcal{X}_2) + \hat{g}(\check{\nabla}_{\mathcal{X}_1}\hat{\zeta}, \mathcal{X}_2) + \hat{g}(\mathcal{X}_1, \check{\nabla}_{\mathcal{X}_2}\hat{\zeta}). \tag{6.49}$$

Now using (2.6) and (3.22) in (6.49), we have

$$(\check{\mathcal{L}}_{\hat{\zeta}}\hat{g})(\mathcal{X}_1, \mathcal{X}_2) = 2\beta[\hat{g}(\mathcal{X}_1, \mathcal{X}_2) - \hat{\eta}(\mathcal{X}_1)\hat{\eta}(\mathcal{X}_2)]. \tag{6.50}$$

Now, from (6.48) and (6.50), we obtain

$$\check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_2) = -(\beta + \Theta)\hat{g}(\mathcal{X}_1, \mathcal{X}_2) + \beta\hat{\eta}(\mathcal{X}_1)\hat{\eta}(\mathcal{X}_2). \tag{6.51}$$

Replacing  $\mathcal{X}_1, \mathcal{X}_2$  by  $\hat{\zeta}$  and using (6.43), we get

$$\Theta = 2n(\beta^2 + \hat{\zeta}\beta).$$

Since  $\beta$  is some non-zero function, we have  $\Theta \neq 0$ , so we state the following theorem:

**Theorem 6.2.** *A Ricci soliton  $(\hat{g}, \hat{\zeta}, \Theta)$  in  $\beta$ -Kenmotsu manifold  $\Omega^{2n+1}$  with  $\hat{\nabla}$  can not be steady but is expanding if  $\beta^2 + \hat{\zeta}\beta > 0$  and shrinking if  $\beta^2 + \hat{\zeta}\beta < 0$ .*

## 7. EXAMPLE OF $\beta$ -KENMOTSU MANIFOLD WITH NON-SYMMETRIC NON-METRIC CONNECTION

**Example 7.1.** *Let us consider the 3-dimensional manifold  $\Omega^{2n+1} = [(x; y; z) \in \mathcal{R}^3 | z \neq 0]$ ; where  $(x; y; z)$  are the standard coordinates in  $\mathcal{R}^3$ . Consider the vector fields*

$$\varrho_1 = z^2 \frac{\partial}{\partial x}, \quad \varrho_2 = z^2 \frac{\partial}{\partial y}, \quad \varrho_3 = \frac{\partial}{\partial z} = \hat{\zeta}.$$

At each point of  $\Omega^{2n+1}$ ,  $\varrho_1, \varrho_2$  and  $\varrho_3$  are linearly independent. Suppose the Riemannian metric  $\hat{g}$  is defined as

$$\begin{aligned} \hat{g}(\varrho_1, \varrho_2) &= \hat{g}(\varrho_2, \varrho_3) = \hat{g}(\varrho_3, \varrho_1) = 0, \\ \hat{g}(\varrho_1, \varrho_1) &= \hat{g}(\varrho_2, \varrho_2) = \hat{g}(\varrho_3, \varrho_3) = 1, \end{aligned} \tag{7.52}$$

and  $\hat{\varphi}$  is defined by

$$\hat{\varphi}(\varrho_1) = -\varrho_2, \quad \hat{\varphi}(\varrho_2) = \varrho_1, \quad \hat{\varphi}(\varrho_3) = 0. \tag{7.53}$$

According to the Lie bracket definition, we get

$$[\varrho_1, \varrho_2] = 0, \quad [\varrho_1, \varrho_3] = -\frac{2}{z}\varrho_1, \quad [\varrho_2, \varrho_3] = -\frac{2}{z}\varrho_2. \tag{7.54}$$

Also

$$\begin{aligned} 2\hat{g}(\hat{\nabla}_{\mathcal{X}_1}\mathcal{X}_2, \mathcal{X}_3) &= \mathcal{X}_1\hat{g}(\mathcal{X}_2, \mathcal{X}_3) + \mathcal{X}_2\hat{g}(\mathcal{X}_3, \mathcal{X}_1) - \mathcal{X}_3\hat{g}(\mathcal{X}_1, \mathcal{X}_2) \\ &+ \hat{g}([\mathcal{X}_1, \mathcal{X}_2], \mathcal{X}_3) - \hat{g}([\mathcal{X}_2, \mathcal{X}_3], \mathcal{X}_1) + \hat{g}([\mathcal{X}_3, \mathcal{X}_1], \mathcal{X}_2). \end{aligned} \tag{7.55}$$

Using Koszul's formula, we get

$$\begin{aligned} \hat{\nabla}_{\varrho_1}\varrho_1 &= \frac{2}{z}\varrho_3, \quad \hat{\nabla}_{\varrho_1}\varrho_2 = 0, \quad \hat{\nabla}_{\varrho_1}\varrho_3 = -\frac{2}{z}\varrho_1, \\ \hat{\nabla}_{\varrho_2}\varrho_1 &= 0, \quad \hat{\nabla}_{\varrho_2}\varrho_2 = \frac{2}{z}\varrho_3, \quad \hat{\nabla}_{\varrho_2}\varrho_3 = -\frac{2}{z}\varrho_2, \\ \hat{\nabla}_{\varrho_3}\varrho_1 &= 0, \quad \hat{\nabla}_{\varrho_3}\varrho_2 = 0, \quad \hat{\nabla}_{\varrho_3}\varrho_3 = 0. \end{aligned} \tag{7.56}$$

Also  $\mathcal{X}_1 = \mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3$  and  $\hat{\zeta} = \varrho_3$ , then we have

$$\begin{aligned} \hat{\nabla}_{\mathcal{X}_1} \hat{\zeta} &= \hat{\nabla}_{\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3} \varrho_3 \\ &= \mathcal{X}^1 \hat{\nabla}_{\varrho_1} \varrho_3 + \mathcal{X}^2 \hat{\nabla}_{\varrho_2} \varrho_3 + \mathcal{X}^3 \hat{\nabla}_{\varrho_3} \varrho_3 \\ &= -\frac{2}{z} (\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2) \end{aligned} \tag{7.57}$$

and

$$\begin{aligned} \hat{\nabla}_{\mathcal{X}_1} \hat{\zeta} &= \beta[\mathcal{X}_1 - \hat{\eta}(\mathcal{X}_1)\hat{\zeta}] \\ &= \beta[(\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3) - \hat{g}(\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3, \varrho_3) \varrho_3] \\ &= -\frac{2}{z} [\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3 - \mathcal{X}^3 \varrho_3] \\ &= -\frac{2}{z} [\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2]. \end{aligned} \tag{7.58}$$

From (7.57) and (7.58), the structure  $(\hat{\varphi}, \hat{\zeta}, \hat{\eta}, \hat{g})$  is a  $\beta$ -Kenmotsu manifold structure. Therefore  $\Omega^3(\hat{\varphi}, \hat{\zeta}, \hat{\eta}, \hat{g})$  is a  $\beta$ -Kenmotsu manifold. From (2.3), (2.5), (3.17) and (7.56), we have

$$\begin{aligned} \check{\nabla}_{\varrho_1} \varrho_1 &= \frac{2}{z} \varrho_3, & \check{\nabla}_{\varrho_1} \varrho_2 &= -\varrho_3, & \check{\nabla}_{\varrho_1} \varrho_3 &= -\frac{2}{z} \varrho_1, \\ \check{\nabla}_{\varrho_2} \varrho_1 &= \varrho_3, & \check{\nabla}_{\varrho_2} \varrho_2 &= \frac{2}{z} \varrho_3, & \check{\nabla}_{\varrho_2} \varrho_3 &= -\frac{2}{z} \varrho_2, \\ \check{\nabla}_{\varrho_3} \varrho_1 &= 0, & \check{\nabla}_{\varrho_3} \varrho_2 &= 0, & \check{\nabla}_{\varrho_3} \varrho_3 &= 0. \end{aligned} \tag{7.59}$$

From equations (3.18) and (3.19), we have

$$\check{\mathcal{T}}'(\varrho_1, \varrho_2) = 2\hat{g}(\hat{\varphi}\varrho_1, \varrho_2) = -2\varrho_3 \neq 0$$

and

$$\begin{aligned} (\check{\nabla}_{\varrho_1} \hat{g})(\varrho_2, \varrho_3) &= -\hat{\eta}(\varrho_3)\hat{g}(\hat{\varphi}\varrho_1, \varrho_2) - \hat{\eta}(\varrho_2)\hat{g}(\hat{\varphi}\varrho_1, \varrho_3) \\ &= 1 \neq 0. \end{aligned}$$

Consequently, a non-symmetric non-metric connection  $\check{\nabla}$  is defined in (3.17). Also,

$$\begin{aligned} \check{\nabla}_{\mathcal{X}_1} \hat{\zeta} &= \check{\nabla}_{\mathcal{X}^1 \varrho_1 + \mathcal{X}^2 \varrho_2 + \mathcal{X}^3 \varrho_3} \varrho_3 \\ &= \mathcal{X}^1 \check{\nabla}_{\varrho_1} \varrho_3 + \mathcal{X}^2 \check{\nabla}_{\varrho_2} \varrho_3 + \mathcal{X}^3 \check{\nabla}_{\varrho_3} \varrho_3 \\ &= -\frac{2}{z} \mathcal{X}^1 \varrho_1 - \frac{2}{z} \mathcal{X}^2 \varrho_2, \end{aligned} \tag{7.60}$$

The equation (3.22) can be verified using equations (7.57) and (7.60).

The components of  $\mathcal{R}^\dagger$  of  $\hat{\nabla}$  are defined as

$$\mathcal{R}^\dagger(\varrho_1, \varrho_2)\varrho_1 = \frac{4}{z^2}\varrho_2, \mathcal{R}^\dagger(\varrho_1, \varrho_3)\varrho_1 = \frac{4}{z^2}\varrho_3, \mathcal{R}^\dagger(\varrho_2, \varrho_3)\varrho_1 = 0,$$

$$\mathcal{R}^\dagger(\varrho_1, \varrho_2)\varrho_2 = -\frac{4}{z^2}\varrho_1, \mathcal{R}^\dagger(\varrho_1, \varrho_3)\varrho_2 = 0, \mathcal{R}^\dagger(\varrho_2, \varrho_3)\varrho_2 = \frac{4}{z^2}\varrho_3, \quad (7.61)$$

$$\mathcal{R}^\dagger(\varrho_1, \varrho_2)\varrho_3 = 0, \mathcal{R}^\dagger(\varrho_1, \varrho_3)\varrho_3 = -\frac{4}{z^2}\varrho_1, \mathcal{R}^\dagger(\varrho_2, \varrho_3)\varrho_3 = -\frac{4}{z^2}\varrho_2,$$

hence we can verify the equations (2.8), (2.9), (2.10) and (2.12).

Similarly, the components of curvature tensor  $\check{\mathcal{R}}^\dagger$  of connection  $\check{\nabla}$  are as under:

$$\check{\mathcal{R}}^\dagger(\varrho_1, \varrho_2)\varrho_1 = \frac{4}{z^2}\varrho_2 - \frac{2}{z}\varrho_1, \check{\mathcal{R}}^\dagger(\varrho_1, \varrho_3)\varrho_1 = \frac{4}{z^2}\varrho_3, \check{\mathcal{R}}^\dagger(\varrho_2, \varrho_3)\varrho_1 = \frac{2}{z}\varrho_3,$$

$$\check{\mathcal{R}}^\dagger(\varrho_1, \varrho_2)\varrho_2 = -\frac{4}{z^2}\varrho_1 - \frac{2}{z}\varrho_2, \check{\mathcal{R}}^\dagger(\varrho_1, \varrho_3)\varrho_2 = -\frac{2}{z}\varrho_3, \check{\mathcal{R}}^\dagger(\varrho_2, \varrho_3)\varrho_2 = \frac{4}{z^2}\varrho_3, \quad (7.62)$$

$$\check{\mathcal{R}}^\dagger(\varrho_1, \varrho_2)\varrho_3 = \frac{4}{z}\varrho_3, \check{\mathcal{R}}^\dagger(\varrho_1, \varrho_3)\varrho_3 = -\frac{4}{z^2}\varrho_1, \check{\mathcal{R}}^\dagger(\varrho_2, \varrho_3)\varrho_3 = -\frac{4}{z^2}\varrho_2.$$

Thus, we can verify (4.24), (4.28), (4.29) and (4.30).

$\mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_2)$  of connection  $\hat{\nabla}$  can be derived by using (7.61) in

$\mathcal{S}^\dagger(\mathcal{X}_1, \mathcal{X}_2) = \sum_{i=1}^3 \hat{g}(\mathcal{R}^\dagger(\varrho_i, \mathcal{X}_1)\mathcal{X}_2, \varrho_i)$ . It is as under:

$$\mathcal{S}^\dagger(\varrho_1, \varrho_1) = \mathcal{S}^\dagger(\varrho_2, \varrho_2) = \mathcal{S}^\dagger(\varrho_3, \varrho_3) = -\frac{8}{z^2}. \quad (7.63)$$

$\check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_1)$  of connection  $\check{\nabla}$  can be derived by using equation (7.62) in

$\check{\mathcal{S}}^\dagger(\mathcal{X}_1, \mathcal{X}_2) = \sum_{i=1}^3 \check{g}(\check{\mathcal{R}}^\dagger(\varrho_i, \mathcal{X}_1)\mathcal{X}_2, \varrho_i)$ . It is as follows:

$$\check{\mathcal{S}}^\dagger(\varrho_1, \varrho_1) = \check{\mathcal{S}}^\dagger(\varrho_2, \varrho_2) = \check{\mathcal{S}}^\dagger(\varrho_3, \varrho_3) = -\frac{8}{z^2}. \quad (7.64)$$

In view of (7.63) and (7.64), the scalar curvature can be calculated as under:

$$k = \sum_{i=1}^3 \mathcal{S}^\dagger(\varrho_i, \varrho_i) = \mathcal{S}^\dagger(\varrho_1, \varrho_1) + \mathcal{S}^\dagger(\varrho_2, \varrho_2) + \mathcal{S}^\dagger(\varrho_3, \varrho_3) = -\frac{24}{z^2},$$

$$\check{k} = \sum_{i=1}^3 \check{\mathcal{S}}^\dagger(\varrho_i, \varrho_i) = \check{\mathcal{S}}^\dagger(\varrho_1, \varrho_1) + \check{\mathcal{S}}^\dagger(\varrho_2, \varrho_2) + \check{\mathcal{S}}^\dagger(\varrho_3, \varrho_3) = -\frac{24}{z^2}.$$

Thus we see that the example also verify Theorem 4.2.

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